iFly Project

Airborne Separation in Advanced En-Route ATM

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Project Facts

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Innovative project for EC DG-TREN (6th Framework)

Consortium: 11 universities + 7 from ATM/aviation iFly project duration: May 2007- August 2010 Total effort: ~ 50 person-years

Builds on theoretical results of HYBRIDGE project for EC DG-INFSO (2002-2005)



Project Consortium

- National Aerospace Laboratory (NLR)
- + Honeywell 🛌
- 🔸 Isdefe 💻
- 🔸 University of Tartu 💻
- Athens University of Economics
 And Business Image
- Eidgenossische Technische Hochschule Zurich
- University of l'Aquila
- + Politecnico di Milano
- + University of Cambridge 💥

- National Technical University of Athens Image
- + University of Twente
- Ecole National de l'Aviation
 Civile
- 🔸 Dedale 🚺
- + UK NATS En Route Ltd. 💥
- Institut National de Recherche en Informatique et en Automatique
- + Eurocontrol EEC
- + DSNA-DTI-SDER
- + University of Leicester 💥



iFly Overview

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What?

iFly's objectives

Why?

Airborne Separation in SESAR/NextGen

How?

Project Structure

Previous Research

Main research areas



iFly Objectives

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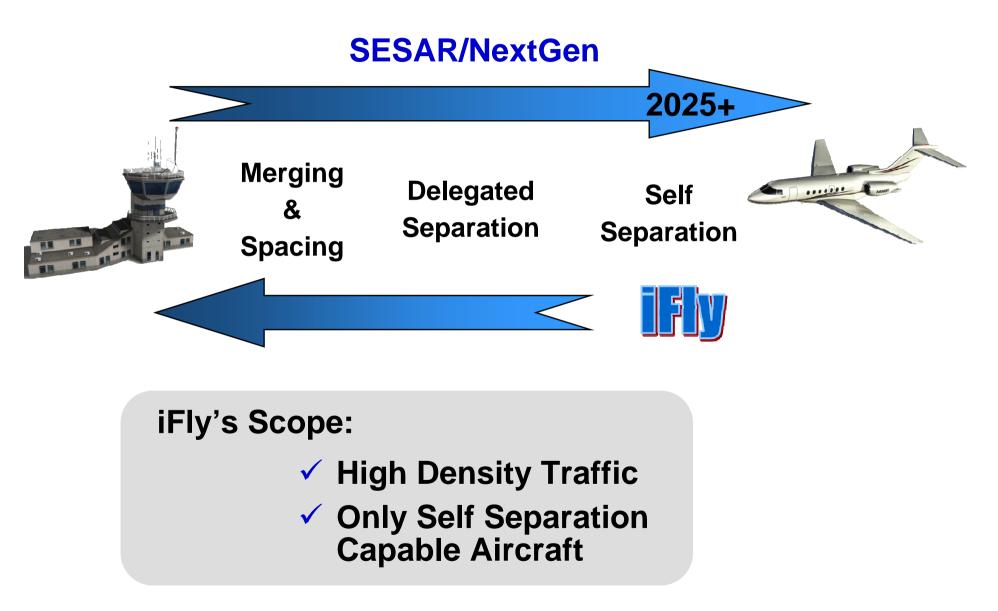
Highly automated ATM design for en-route traffic based on autonomous aircraft concept.

Key design aspects:

- Human responsibilities
- Traffic Complexity
- Safety Assessment using SESAR compliant safety targets

Airborne Separation in Future ATM

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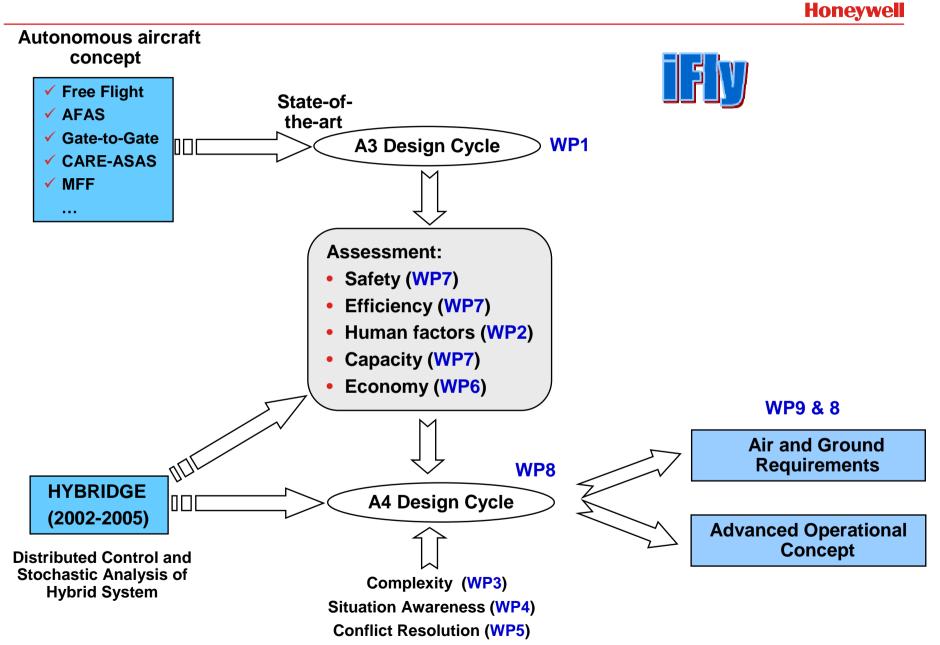


Two Design Cycles To Answer Two Main Research Questions:



- Up to which en route traffic demands is (pure) Self Separation sufficiently safe? (A3 design cycle)
- Which complementary support services from ground ATM are needed in order to accommodate higher traffic demands ? (A4 design cycle)

iFly Project Structure

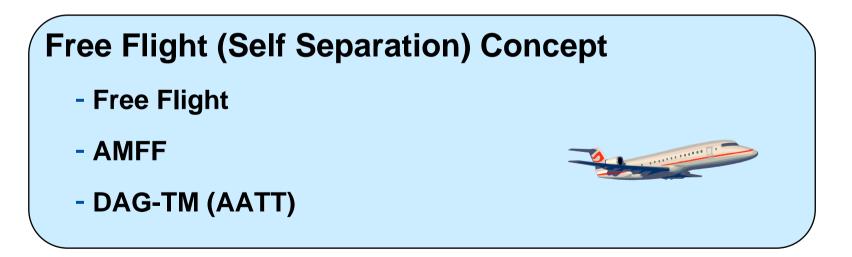


Previous Research

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Theoretical Methods – Hybridge

- Novel methods in rare event modelling and estimation.
- Novel methods in conflict modelling and resolution.
- Accident risk simulation results for Mediterranean Self Separation.



Main Research Areas

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- Safety simulations (rare event modelling)
- Human factors
- Complexity metrics and prediction
- Situation awareness & modelling of complex hybrid systems
- Conflict resolution methods





Hazards Identification

Safety Assessment – Rare event modelling based on the Hybridge project (TOPAZ)

Complex System Modelling – Piecewise Deterministic Markov Processes represented by Dynamically Coloured Petri Nets

Air Traffic Simulation – Sequential Monte Carlo Methods

Relevant Standard considered: RTCA/Eurocae ED78a Safety Assessment

Two Essential Tasks:

- **1. Provide Input To Both Design Cycles**
- 2. Analyse and Identify Bottlenecks of Designed Systems and Propose Solutions

Main Issues

- Analysis of the current pilot's en-route tasks,
- Cockpit crew responsibility analysis,
- Pilot's workload studies
- Situation awareness maintenance
- Identification of bottlenecks

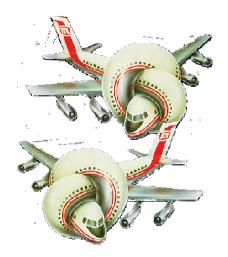


Main Issues

- Complexity has not unique definition.
- Requirements are typically application-dependent.
- Existing metrics of Air Traffic Complexity are mostly related to the controller's workload (e.g., dynamic density).

Considered Approaches

- Intrinsic metrics (not application dependent) e.g., some topological or geometrical characteristic.
- Application dependent tightly related to the CR methods (both airborne or ground-based).



Conflict Resolution

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- Long Term CR Methods (behind one hour)
 - Both centralized (ground-based) and distributed methods
- Mid Term CR (tens of minutes)
 - > Distributed methods, questions of suitable intent information
- Short Term CR (minutes)
 - Distributed methods, interface with TCAS

Main Issues

- Choice of suitable CR maneuvers
- Priority rules (if needed),
- Coordination of CR maneuvers between conflicting aircraft,
- TP uncertainty handling
- Conflict of multiple aircraft (clustering)
- Optimization (selection) criteria



Vs.

Two parallel approaches:

Conventional

Based on the expert assessment and subsequently validated – used in the both design cycles.

Theoretical (formal)

Based on the modelling of the complex hybrid system and subsequent analysis of the critical observability.



Conclusions

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iFLY objectives

- Assess maximum en-route traffic to be accommodated by self separation
- Develop en-route high traffic demand Self Separation concept (A3).
- Develop complementary ATM ground support concept (A4) which further increases capacity of self separation.

Web site: <u>http://iFLY.nlr.nl</u>

Coordinator: Henk Blom (NLR)

Currently within first design cycle (A3) – High-level ConOps delivered.

Thank You!

